# 8-bit Proprietary Microcontroller

CMOS

# F<sup>2</sup>MC-8L MB89180 Series

# MB89181/182/183/P185/PV180

### DESCRIPTION

The MB89180 series has been developed as a general-purpose version of the F<sup>2</sup>MC\*-8L family consisting of proprietary 8-bit, single-chip microcontrollers.

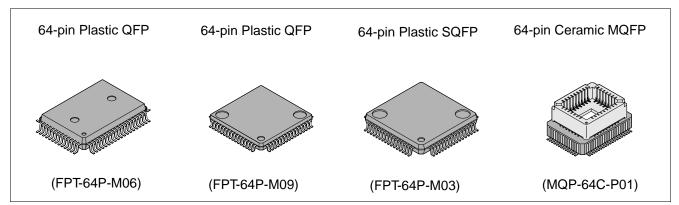
In addition to a compact instruction set, the microcontrollers contain a variety of peripheral functions such as dual-clock control system, five operating speed control stages, timers, a serial interface, a remote control transmission output, external interrupts, an LCD controller/driver, and a watch prescaler.

\*: F<sup>2</sup>MC stands for FUJITSU Flexible Microcontroller.

### ■ FEATURES

- F<sup>2</sup>MC-8L family CPU core
- Dual-clock control system
- High speed operation at low voltage
- Minimum execution time: 0.95  $\mu$ s/2.7 V, 1.33  $\mu$ s/2.2 V
- I/O ports: max. 64 channels
- 21-bit time-base timer
- 8/16-bit timer/counter: 1 channel (8 bits × 2 channels)
- 8-bit serial I/O: 1 channel
- LCD controller/driver: max. 32 segments outputs × 4 commons

(Continued)



### PACKAGE

#### (Continued)

- Remote control transmission output
- Buzzer output
- Watch prescaler (15 bits)
- External interrupts (wake-up function) Four independent channels with edge detection function plus eight "L" level-interrupt channels

## ■ PRODUCT LINEUP

Part number Parameter	MB89181	MB89182	MB89183	MB89P185	MB89PV180
Classification		Mass production products (mask ROM products)			Piggyback/ evaluation product (for evaluation and development)
ROM size	4 K × 8 bits (internal mask ROM)	6 K × 8 bits (internal mask ROM)	8 K × 8 bits (internal mask ROM)	16K × 8 bits (internal PROM, programming with general- purpose EPROM programmer)	32 K × 8 bits (external ROM)
RAM size	$128 \times 8$ bits		$256 \times 8$ bits		$512 \times 8$ bits
CPU functions Ports	Number of instructions:       136         Instruction bit length:       8 bits         Instruction length:       1 to 3 bytes         Data bit length:       1, 8, 16 bits         Minimum execution time:       0.95 µs/4.2 MHz         Interrupt processing time:       8.57 µs/4.2 MHz         I/O ports (N-ch open drain):       8 (6 ports also serve as peripherals, and 3 ports are heavy-current drive type.)         Output ports (N-ch open drain):       18 (16 ports also serve as segment pins*1, and 2 ports serve as booster capacitor connection pins.)         I/O ports (CMOS):       16 (12 ports also serve as an external interrupt, and				pins <sup>*1</sup> , and 2 ports ection pins.) al interrupt, and
	Output port (C Total:			erve as segment p a remote control pi	
8/16-bit timer/ counter	8-bit ti	mer/counter ×2	channels or 16-bit	event counter $\times$ 1	channel
8-bit serial I/O		LSB	8 bits first/MSB first sele	ctability	
LDC controller/driver	Common output:4 (COM2 and COM3 also serve as output porSegment output:32 (max.)*1Bias power supply pins:3LCD display RAM size:32 × 4 bitsDividing resistor for LCD driving (external resistor selectability)				utput ports.)
External interrupt (wake-up function)	4		election, also serv els (only for a leve	e as segment pins I interrupt)	.)*1

(Continued)

Part number Parameter	MB89181	MB89182	MB89183	MB89P185	MB89PV180	
Buzzer output		1 (7 frequency	types are selectal	ole by software.)		
Remote control transmission output	1 (pulse width and cycle are selectable by software.)					
Standby mode	Sleep mode, stop mode, and watch mode					
Process	CMOS					
Operating voltage*2	2.2 V*3 to 6.0 V 2.7 V to 6.0 V				to 6.0 V	
EPROM for use					MBM27C256A-20TV (LCC package)	

\*1: Selected by the mask option. See section "■ Mask Options."

\*2: Varies with conditions such as the operating frequency and the connected ICE. (See section "■ Electrical Characteristics.")

\*3: The operation at less than 2.2 V is assured separately. Please contact FUJITSU LIMITED.

### ■ PACKAGE AND CORRESPONDING PRODUCTS

Package	MB89181 MB89182 MB89183	MB89P185	MB89PV180
FPT-64P-M06	0	0	×
FPT-64P-M09	0	0	×
FPT-64P-M03	0	×	×
MQP-64C-P01	×	×	0

 $\bigcirc$  : Available  $\times$  : Not available

Note: For more information about each package, see section "
Package Dimensions."

### DIFFERENCES AMONG PRODUCTS

#### 1. Memory Size

Before evaluating using the piggyback product, verify its differences from the product that will actually be used. Take particular care on the following points:

- On the MB89181, addresses 0140H and later of the register bank cannot be used. On the MB89182, MB89183, and MB89P185 microcontrollers, addresses 0180H and later of the register bank cannot be used.
- On the MB89P185, addresses BFF0<sub>H</sub> to BFF5<sub>H</sub> comprise the option setting area, option settings can be read by reading these addresses.
- The stack area, etc., is set at the upper limit of the RAM.

#### 2. Current Consumption

- In the case of the MB89PV180, add the current consumed by the EPROM which is connected to the top socket.
- When operated at low speed, the product with an OTPROM (one-time PROM) or an EPROM will consume more current than the product with a mask ROM.

However, the current consumption in sleep/stop modes is the same. (For more information, see section "■ Electrical Characteristics." )

#### 3. Mask Options

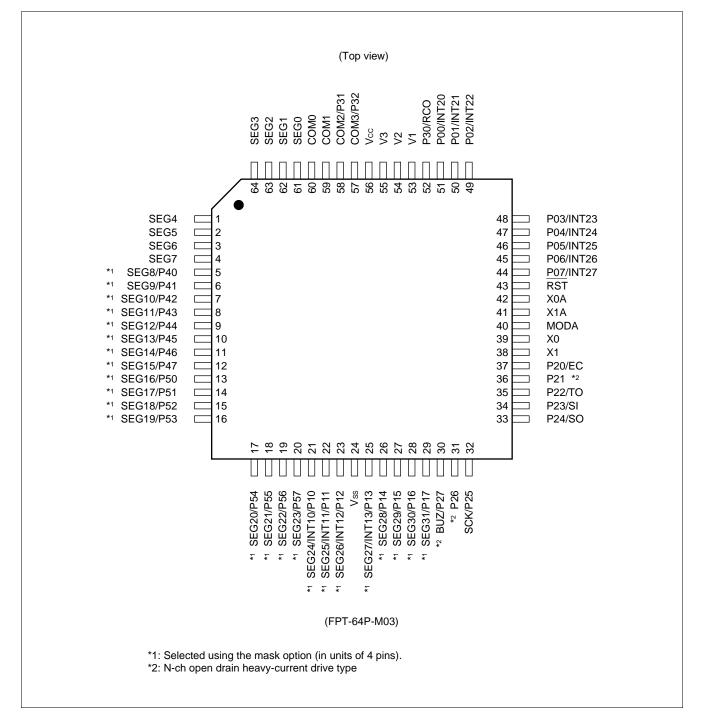
Functions that can be selected as options and how to designate these options vary by the product.

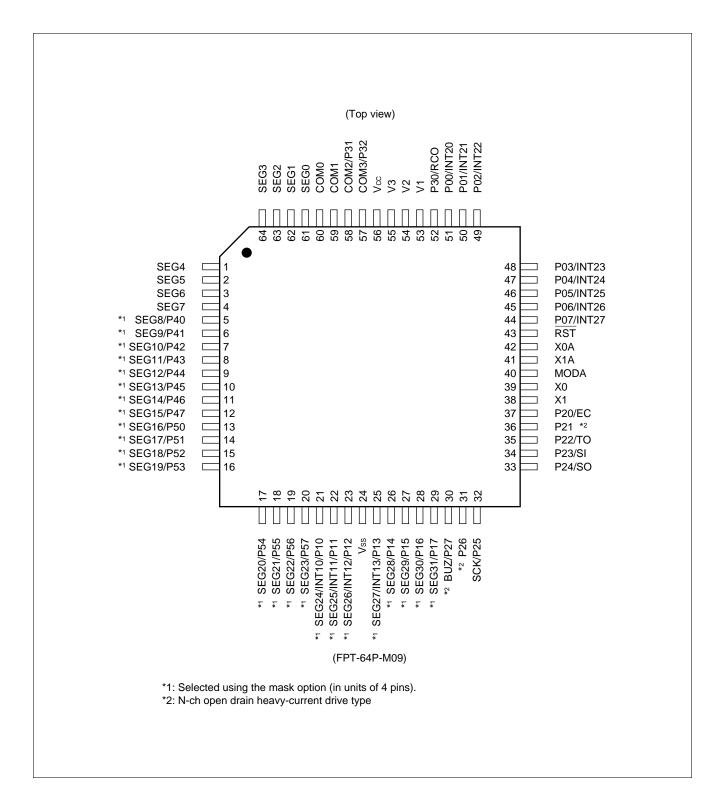
Before using options check section "Mask Options."

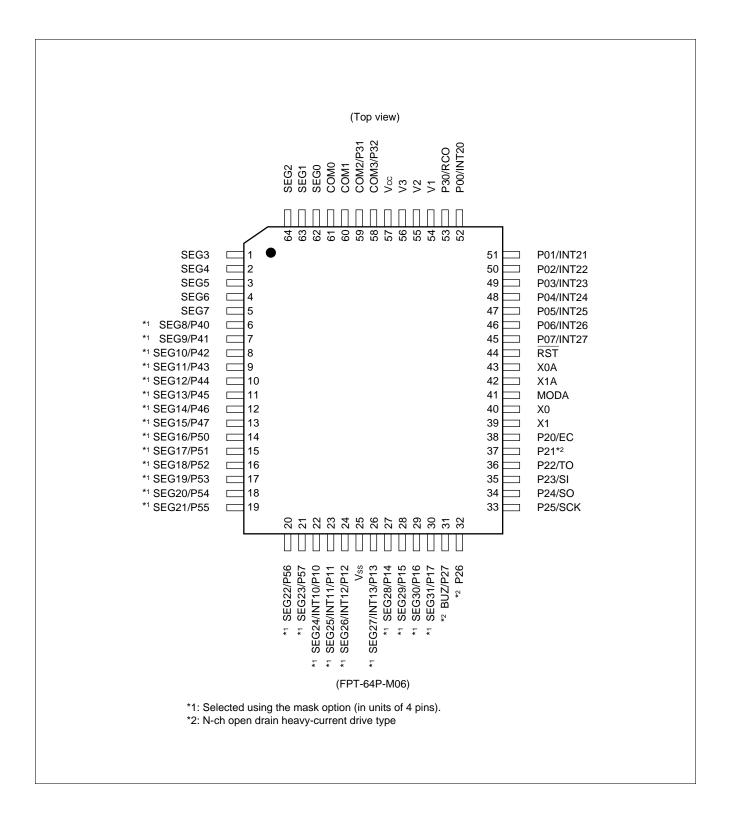
Take particular care on the following point:

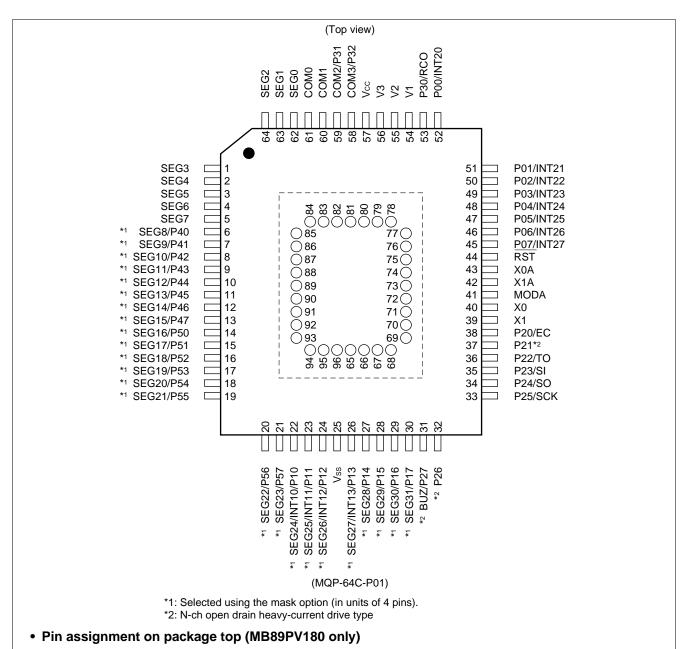
• Options are fixed on the MB89PV180 except the segment output selection.

#### ■ PIN ASSIGNMENT









Pin no.	Pin name						
65	N.C.	73	A2	81	N.C.	89	ŌE
66	Vpp	74	A1	82	O4	90	N.C.
67	A12	75	A0	83	O5	91	A11
68	A7	76	N.C.	84	O6	92	A9
69	A6	77	O1	85	07	93	A8
70	A5	78	O2	86	O8	94	A13
71	A4	79	O3	87	CE	95	A14
72	A3	80	Vss	88	A10	96	Vcc

N.C.: Internally connected. Do not use.

### ■ PIN DESCRIPTION

Pin	no.		<b>a</b>		
QFP <sup>*1</sup> SQFP <sup>*3</sup>	QFP <sup>*2</sup> MQFP <sup>*4</sup>	Pin name	Circuit type	Function	
39	40	X0	A	Main clock crystal oscillator pins	
38	39	X1		CR oscillation selectability (only for the mask ROM products)	
40	41	MODA	С	Operating mode selection pin Connect directly to Vss.	
43	44	RST	D	Reset I/O pin This pin is an N-ch open drain output type with a pull- up resistor, and hysteresis input type. "L" is output from this pin by an internal reset source. The internal circuit is initialized by the input of "L".	
44 to 51	45 to 52	P07/INT27 to P00/INT20	E	General-purpose I/O ports Also serve as external interrupt 2 input (wake-up function). External interrupt 2 input is hysteresis input.	
21 to 23	22 to 24	P10/INT10/ SEG24 to P12/INT12/ SEG26	E/K	General-purpose I/O ports Also serve as external interrupt 1 input. The interrupt 1 input is a hysteresis type. Also serve as LCD controller/driver segment outpu	
25	26	P13/INT13/ SEG27		Switching is done by the mask option.	
26 to 29	27 to 30	P14/SEG28 to P17/SEG31	F/K	General-purpose I/O ports Also serve as LCD controller/driver segment output. Switching is done by the mask option.	
37	38	P20/EC	Н	General-purpose N-ch open-drain I/O port Also serves as the external clock input for the 8-bit timer counter. The resource is a hysteresis input type.	
36	37	P21	I	General-purpose N-ch open-drain I/O port	
35	36	P22/TO	I	General-purpose N-ch open-drain I/O port Also serves as the 8-bit timer/counter output	
34	35	P23/SI	Н	General-purpose N-ch open-drain I/O port Also serves as the data input for the 8-bit serial I/O. The resource is a hysteresis input type.	
33	34	P24/SO	I	General-purpose N-ch open-drain I/O port Also serves as the data output for the 8-bit serial I/O.	
32	33	P25/SCK	н	General-purpose N-ch open-drain I/O port Also serves as the clock I/O for the 8-bit serial I/O. The resource is a hysteresis input type.	

\*1: FPT-64P-M09

\*2: FPT-64P-M06

\*3: FPT-64P-M03

\*4: MQP-64C-P01

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Pin	no.		Circuit	
QFP <sup>*1</sup> SQFP <sup>*3</sup>	QFP <sup>*2</sup> MQFP <sup>*4</sup>	Pin name	type	Function
31	32	P26	I	General-purpose N-ch open-drain I/O port
30	31	P27/BUZ	I	General-purpose N-ch open-drain I/O port Also serves as a buzzer output.
52	53	P30/RCO	G	General-purpose output-only port Also serves as a remote control transmission output pin.
13 to 20	14 to 21	P50/SEG16 to P57/SEG23	J/K	N-ch open-drain type general-purpose output ports Also serve as LCD controller/driver segment output
5 to 12	6 to 13	P40/SEG8 to P47/SEG15	J/K	pins. Switching is done by the mask option.
61 to 64, 1 to 4	62 to 64, 1 to 5	SEG7 to SEG0	К	LCD controller/driver segment output-only pins
57, 58	58, 59	COM3/P32, COM2/P31	L	N-ch open-drain type general-purpose output ports Also serve as LCD controller/driver common output pins.
59, 60	60, 61	COM1, COM0	К	LCD controller/driver common output-only pins
53, 54, 55	54, 55, 56	V1, V2, V3	_	LCD driving power supply pins
42	43	X0A	В	Subclock crystal oscillator pins (32.768 kHz)
41	42	X1A		
56	57	Vcc		Power supply pin
24	25	Vss		Power supply (GND) pin

\*1: FPT-64P-M09

\*2: FPT-64P-M06

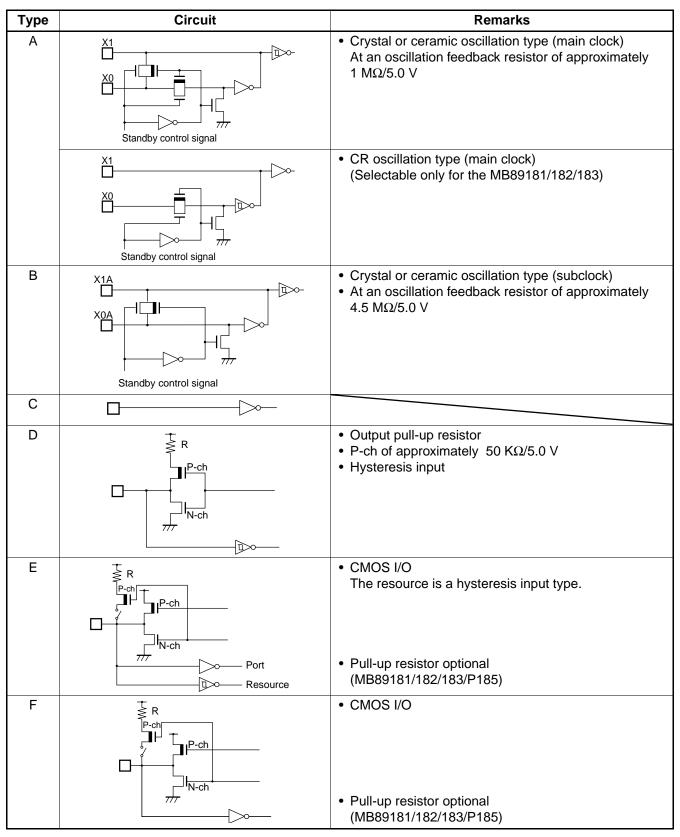
\*3: FPT-64P-M03

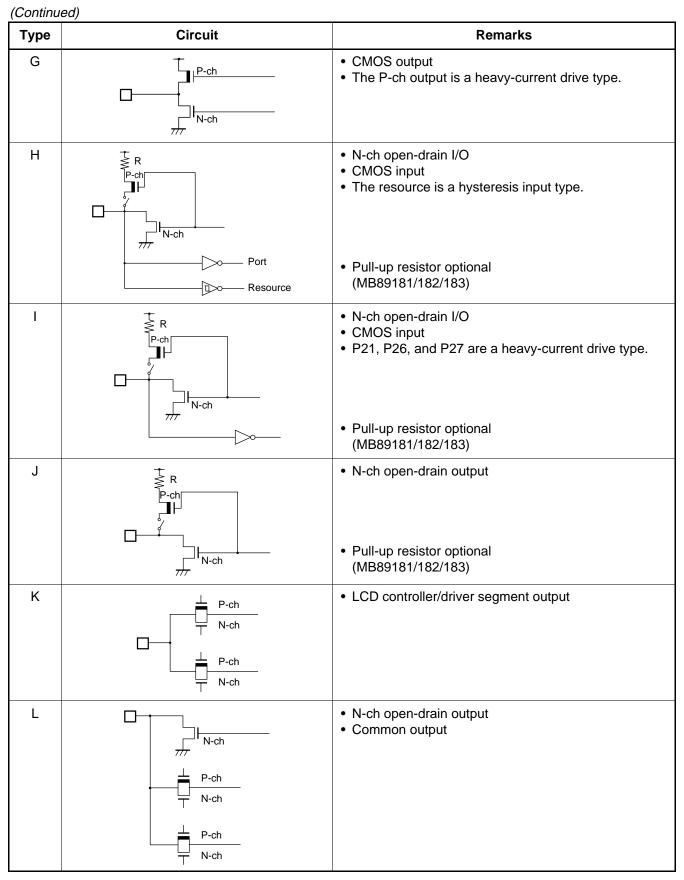
\*4: MQP-64C-P01

Pin no.	Pin name	I/O	Function
66	Vpp	0	"H" level output pin
67 68 69 70 71 72 73 74 75	A12 A7 A6 A5 A4 A3 A2 A1 A0	Ο	Address output pins
77 78 79	01 02 03	I	Data input pins
80	Vss	0	Power supply (GND) pin
82 83 84 85 86	04 05 06 07 08	I	Data input pins
87	CE	0	ROM chip enable pin Outputs "H" during standby.
88	A10	0	Address output pin
89	ŌĒ	0	ROM output enable pin Outputs "L" at all times.
91 92 93	A11 A9 A8	0	Address output pins
94	A13	0	
95	A14	0	
96	Vcc	0	EPROM power supply pin
65 76 81 90	N.C.		Internally connected pins Be sure to leave them open.

• External EPROM pins (MB89PV180 only)

### ■ I/O CIRCUIT TYPE





### ■ HANDLING DEVICES

#### 1. Preventing Latchup

Latchup may occur on CMOS ICs if voltage higher than Vcc or lower than Vss is applied to input and output pins other than medium- to high-voltage pins or if higher than the voltage which shows on "1. Absolute Maximum Ratings" in section "■ Electrical Characteristics" is applied between Vcc and Vss.

When latchup occurs, power supply current increases rapidly and might thermally damage elements. When using, take great care not to exceed the absolute maximum ratings.

Also, take care to prevent the analog power supply (AVcc and AVR) and analog input from exceeding the digital power supply (Vcc) when the analog system power supply is turned on and off.

#### 2. Treatment of Unused Input Pins

Leaving unused input pins open could cause malfunctions. They should be connected to a pull-up or pull-down resistor.

#### 3. Treatment of Power Supply Pins on Microcontrollers with A/D and D/A Converters

Connect to be AVcc = DAVC = Vcc and AVss = AVR = Vss even if the A/D and D/A converters are not in use.

#### 4. Treatment of N.C. Pins

Be sure to leave (internally connected) N.C. pins open.

#### 5. Power Supply Voltage Fluctuations

Although V<sub>CC</sub> power supply voltage is assured to operate within the rated range, a rapid fluctuation of the voltage could cause malfunctions, even if it occurs within the rated range. Stabilizing voltage supplied to the IC is therefore important. As stabilization guidelines, it is recommended to control power so that V<sub>CC</sub> ripple fluctuations (P-P value) will be less than 10% of the standard V<sub>CC</sub> value at the commercial frequency (50 to 60 Hz) and the transient fluctuation rate will be less than 0.1 V/ms at the time of a momentary fluctuation such as when power is switched.

#### 6. Precautions when Using an External Clock

Even when an external clock is used, oscillation stabilization time is required for power-on reset (optional) and wake-up from stop mode.

### ■ PROGRAMMING TO THE EPROM ON THE MB89P875

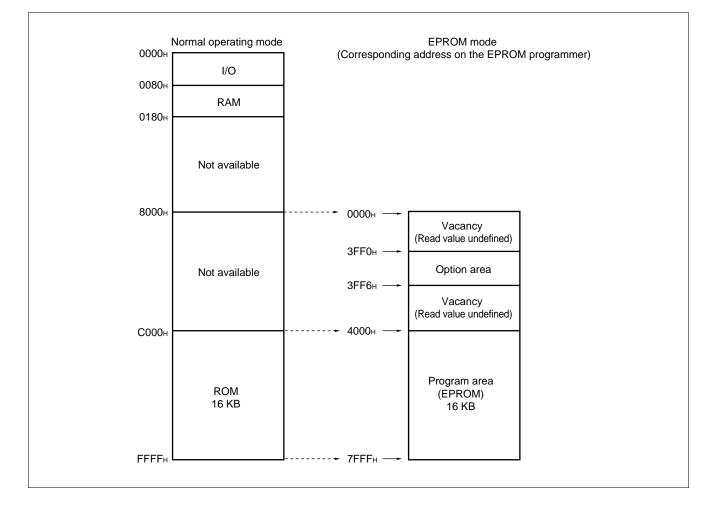
The MB89P185 is an OTPROM version of the MB89180 series.

#### 1. Features

- 16-Kbyte PROM on chip
- Options can be set using the EPROM programmer.
- Equivalency to the MBM27C256A in EPROM mode (when programmed with the EPROM programmer)

#### 2. Memory Space

Memory space in the EPROM mode is diagrammed below.



#### 3. Programming to the EPROM

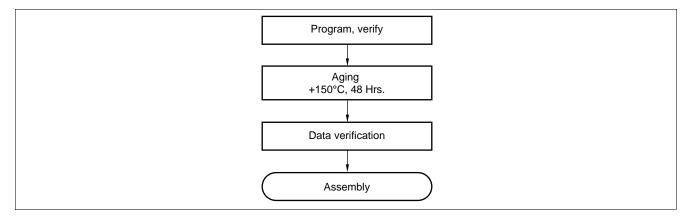
In EPROM mode, the MB89P185 functions equivalent to the MBM27C256A. This allows the PROM to be programmed with a general-purpose EPROM programmer (the electronic signature mode cannot be used) by using the dedicated socket adapter.

#### • Programming procedure

- (1) Set the EPROM programmer to the MBM27C256A.
- (2) Load program data into the EPROM programmer at 4000<sub>H</sub> to 7FFF<sub>H</sub> (note that addresses C000<sub>H</sub> to FFFF<sub>H</sub> in operating mode assign to 4000<sub>H</sub> to 7FFF<sub>H</sub> in EPROM mode). Program to 4000<sub>H</sub> to 7FFF<sub>H</sub> with the EPROM programmer.
- (3) Load option data into addresses 3FF0H to 3FF5H of the EPROM programmer. (For information about each corresponding option, see "7. PROM Option Bit Map.") Program to 3FF0H to 3FF5H with the EPROM programmer.

#### 4. Recommended Screening Conditions

High-temperature aging is recommended as the pre-assembly screening procedure for a product with a blanked OTPROM microcomputer program.



#### 5. Programming Yield

All bits cannot be programmed at Fujitsu shipping test to a blanked OTPROM microcomputer, due to its nature. For this reason, a programming yield of 100% cannot be assured at all times.

#### 6. EPROM Programmer Socket Adapter

Package	Compatible socket adapter
FPT-64P-M09	ROM-64QF2-28DP-8L2
FPT-64P-M06	ROM-64QF-28DP-8L3

Inquiry: Sun Hayato Co., Ltd.: TEL 81-3-3802-5760

Note: Depending on the EPROM programmer, inserting a capacitor of about 0.1  $\mu$ F between V<sub>PP</sub> and V<sub>SS</sub> or V<sub>cc</sub> and V<sub>SS</sub> can stabilize programming operations.

### 7. PROM Option Bit Map

The programming procedure is the same as that for the PROM. Options can be set by programming values at the addresses shown on the memory map. The relationship between bits and options is shown on the following bit map:

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
	Vacancy	Vacancy	Oscillation stabili	zation delay time	Vacancy	Reset pin output	Clock mode selection	Power-on reset
3FF0⊦	Readable	Readable	WTM1 See " <b>■</b> Ma	WTM0 sk Options"	Readable	1: Yes 0: No	1: Dual clock 0: Single clock	1: Yes 0: No
3FF1н	P07	P06	P05	P04	P03	P02	P01	P00
	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up
	1: No	1: No	1: No	1: No	1: No	1: No	1: No	1: No
	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes
3FF2н	P17	P16	P15	P14	P13	P12	P11	P10
	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up	Pull-up
	1: No	1: No	1: No	1: No	1: No	1: No	1: No	1: No
	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes	0: Yes
3FF3⊦	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy
	Readable	Readable	Readable	Readable	Readable	Readable	Readable	Readable
3FF4⊦	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy
	Readable	Readable	Readable	Readable	Readable	Readable	Readable	Readable
3FF5⊦	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy	Vacancy
	Readable	Readable	Readable	Readable	Readable	Readable	Readable	Readable

Notes: • Set each bit to 1 to erase.

• Do not write 0 to the vacant bit.

The read value of the vacant bit is 1, unless 0 is written to it.

 $\bullet$  Address 3FF6 $\!\scriptscriptstyle H$  cannot be read and should not be accessed.

### ■ PROGRAMMING TO THE EPROM WITH PIGGYBACK/EVALUATION DEVICE

#### 1. EPROM for Use

MBM27C256A-20TV

#### 2. Programming Socket Adapter

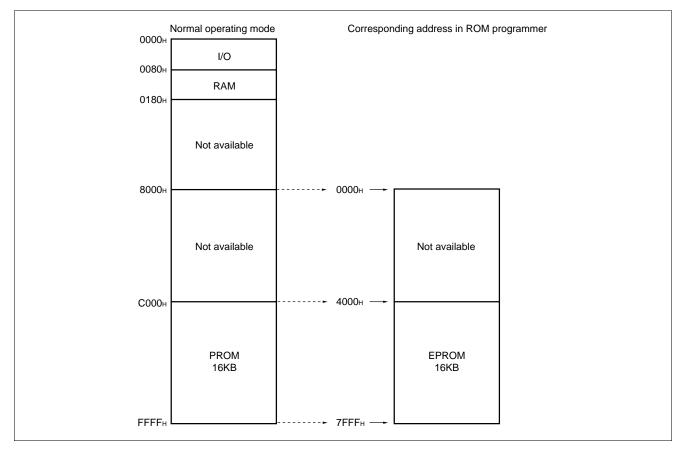
To program to the PROM using an EPROM programmer, use the socket adapter (manufacturer: Sun Hayato Co., Ltd.) listed below.

Package	Adapter socket part number	
LCC-32(Rectangle)	ROM-32LC-28DP-YG	
LCC-32(Square)	ROM-32LC-28DP-S	

Inquiry: Sun Hayato Co., Ltd.: TEL 81-3-3802-5760

#### 3. Memory Space

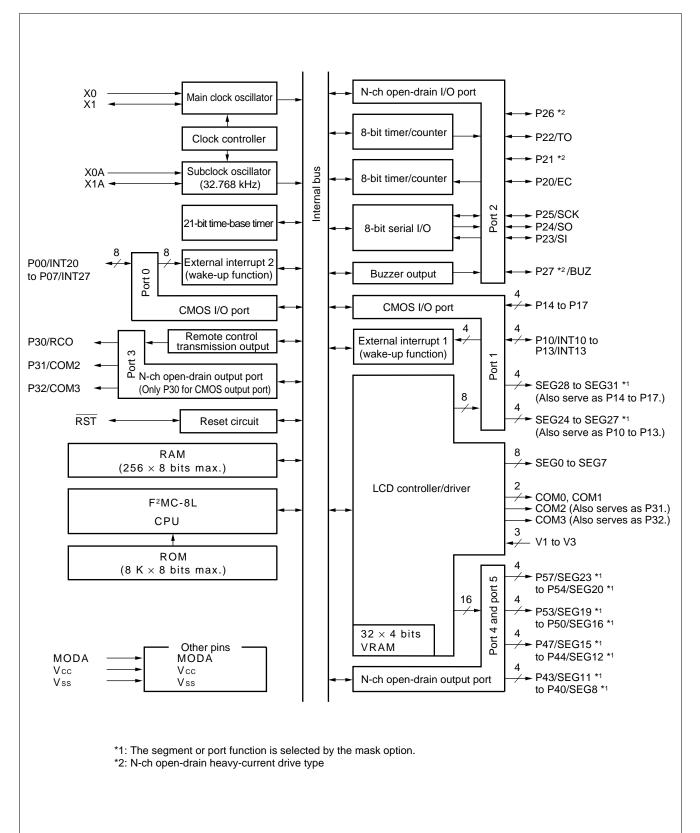
Memory space in each mode is diagrammed below.



#### 4. Programming to the EPROM

- (1) Set the EPROM programmer to the MBM27C256A.
- (2) Load program data into the EPROM programmer at 4000H to 7FFFH.
- (3) Program to  $4000_{\text{H}}$  to  $7FFF_{\text{H}}$  with the EPROM programmer.

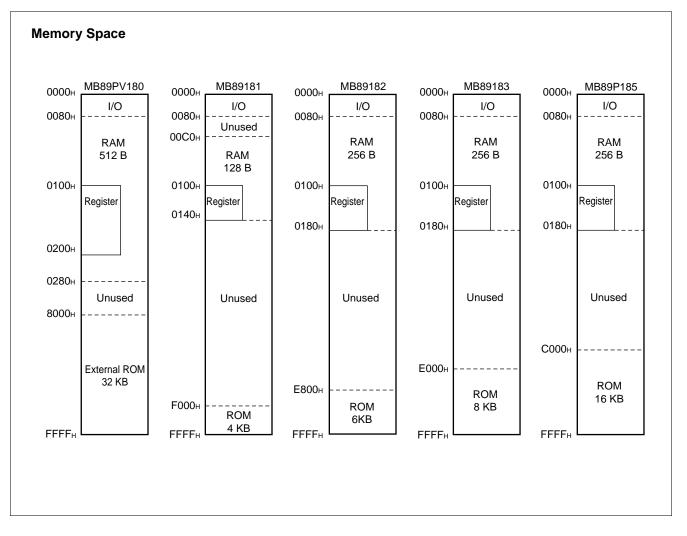
#### BLOCK DIAGRAM



## ■ CPU CORE

#### 1. Memory Space

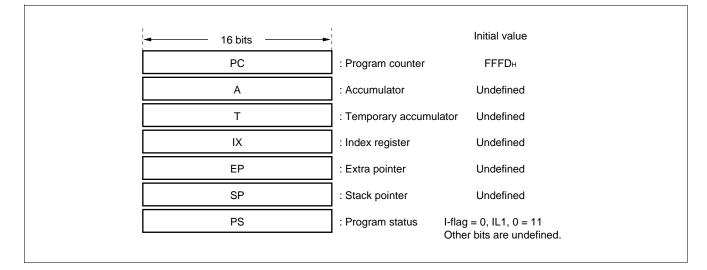
The microcontrollers of the MB89180 series offer a memory space of 64 Kbytes for storing all of I/O, data, and program areas. The I/O area is located at the lowest address. The data area is provided immediately above the I/O area. The data area can be divided into register, stack, and direct areas according to the application. The program area is located at exactly the opposite end, that is, near the highest address. Provide the tables of interrupt reset vectors and vector call instructions toward the highest address within the program area. The memory space of the MB89180 series is structured as illustrated below.



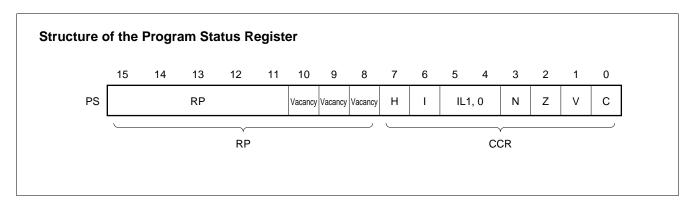
### 2. Registers

The F<sup>2</sup>MC-8L family has two types of registers; dedicated registers in the CPU and general-purpose registers in the memory. The following dedicated registers are provided:

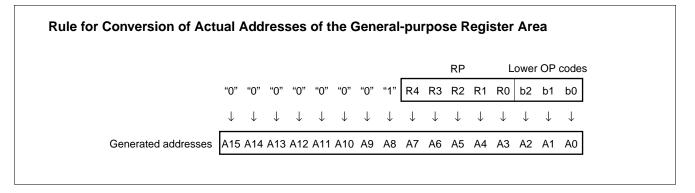
Program counter (PC):	A 16-bit register for indicating instruction storage positions
Accumulator (A):	A 16-bit temporary register for storing arithmetic operations, etc. When the instruction is an 8-bit data processing instruction, the lower byte is used.
Temporary accumulator (T):	A 16-bit register which performs arithmetic operations with the accumulator When the instruction is an 8-bit data processing instruction, the lower byte is used.
Index register (IX):	A 16-bit register for index modification
Extra pointer (EP):	A 16-bit pointer for indicating a memory address
Stack pointer (SP):	A 16-bit register for indicating a stack area
Program status (PS):	A 16-bit register for storing a register pointer, a condition code



The PS can further be divided into higher 8 bits for use as a register bank pointer (RP) and the lower 8 bits for use as a condition code register (CCR). (See the diagram below.)



The RP indicates the address of the register bank currently in use. The relationship between the pointer contents and the actual address is based on the conversion rule illustrated below.



The CCR consists of bits indicating the results of arithmetic operations and the contents of transfer data and bits for control of CPU operations at the time of an interrupt.

- H-flag: Set when a carry or a borrow from bit 3 to bit 4 occurs as a result of an arithmetic operation. Cleared otherwise. This flag is for decimal adjustment instructions.
- I-flag: Interrupt is allowed when this flag is set to 1. Interrupt is prohibited when the flag is set to 0. Set to 0 when reset.
- IL1, 0: Indicates the level of the interrupt currently allowed. Processes an interrupt only if its request level is higher than the value indicated by this bit.

IL1	ILO	Interrupt level	High-low
0	0	1	High
0	1	- I	t
1	0	2	•
1	1	3	Low = no interrupt

N-flag: Set if the MSB is set to 1 as the result of an arithmetic operation. Cleared when the bit is set to 0.

Z-flag: Set when an arithmetic operation results in 0. Cleared otherwise.

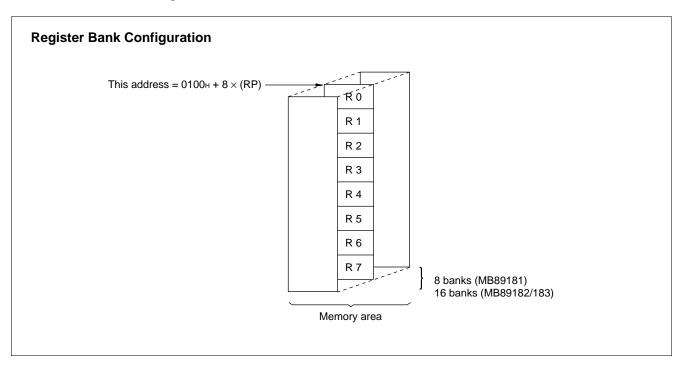
- V-flag: Set if the complement on 2 overflows as a result of an arithmetic operation. Reset if the overflow does not occur.
- C-flag: Set when a carry or a borrow from bit 7 occurs as a result of an arithmetic operation. Cleared otherwise. Set to the shift-out value in the case of a shift instruction.

The following general-purpose registers are provided:

General-purpose registers: An 8-bit register for storing data

The general-purpose registers are 8 bits and located in the register banks of the memory. One bank contains eight registers. Up to a total of 8 banks can be used on the MB89181 (RAM  $128 \times 8$  bits) and a total of 16 banks can be used on the MB89182/183 (RAM  $256 \times 8$  bits). The bank currently in use is indicated by the register bank pointer (RP).

Note: The number of register banks that can be used varies with the RAM size.



### ■ I/O MAP

Address	Read/write	Register name	Register description
00н	(R/W)	PDR0	Port 0 data register
01н	(W)	DDR0	Port 0 data direction register
02н	(R/W)	PDR1	Port 1 data register
03н	(W)	DDR1	Port 1 data direction register
04н	(R/W)	PDR2	Port 2 data register
05н	(W)	DDR2	Port 2 data direction register
06н			Vacancy
07н	(R/W)	SYCC	System clock control register
08н	(R/W)	STBC	Standby control register
09н	(R/W)	WDTC	Watchdog timer control register
0Ан	(R/W)	TBTC	Time-base timer control register
0Вн	(R/W)	WPCR	Watch prescaler control register
ОСн	(R/W)	PDR3	Port 3 data register
0Dн			Vacancy
0Ен	(R/W)	PDR4	Port 4 data register
0Fн	(R/W)	PDR5	Port 5 data register
10н	(R/W)	BZCR	Buzzer register
11н			Vacancy
12н			Vacancy
13н			Vacancy
14н	(R/W)	RCR1	Remote control transmission control register 1
15н	(R/W)	RCR2	Remote control transmission control register 2
16н			Vacancy
17н			Vacancy
18н	(R/W)	T2CR	Timer 2 control register
19н	(R/W)	T1CR	Timer 1 control register
1Ан	(R/W)	T2DR	Timer 2 data register
1Bн	(R/W)	T1DR	Timer 1 data register
1Сн	(R/W)	SMR1	Serial mode register
1Dн	(R/W)	SDR1	Serial mode register
1Ен to 2Fн			Vacancy

(Continued)

Address	Read/write	Register name	Register description
30н	(R/W)	EIE1	External interrupt 1 enable register
31н	(R/W)	EIF1	External interrupt 1 flag register
32н	(R/W)	EIE2	External interrupt 2 enable register
33н	(R/W)	EIF2	External interrupt 2 flag register
34н to 5Fн			Vacancy
60н to 6Fн	(R/W)	VRAM	Display data RAM
70н to 71н			Vacancy
72н	(R/W)	LCR1	LCD controller/driver control register 1
73н to 7Вн			Vacancy
7Сн	(VV)	ILR1	Interrupt level setting register 1
7Dн	(VV)	ILR2	Interrupt level setting register 2
7Ен	(VV)	ILR3	Interrupt level setting register 3
<b>7</b> Fн			Vacancy

#### (Continued)

Note: Do not use vacancies.

# ■ ELECTRICAL CHARACTERISTICS

### 1. Absolute Maximum Ratings

(Vss = 0.0 V)

Demonster	Cumhal	Va	lue	11	Demoske
Parameter	Symbol	Min.	Max.	Unit	Remarks
Power supply voltage	Vcc	Vss-0.3	Vss + 7.0	V	
LCD power supply voltage	V1 to V3	Vss-0.3	Vss + 7.0	V	V1 to V3 must not exceed Vcc.
Input voltage	VI1	Vss-0.3	Vcc + 0.3	V	V <sub>11</sub> must not exceed Vss + 7.0 V. Except P20 to P27 without a pull- up resistor
	V <sub>I2</sub>	Vss-0.3	Vss + 7.0	V	P20 to P27 without a pull-up resistor
Output voltage	Vo1	Vss-0.3	Vcc + 0.3 V		$V_{01}$ must not exceed Vss + 7.0 V. Except P20 to P27, P40 to P47, and P50 to P57 without a pull-up resistor
	V <sub>02</sub>	Vss-0.3	Vss + 7.0	V	P20 to P27, P40 to P47, and P50 to P57 without a pull-up resistor
"L" level output current			10	mA	Except P21, P26, P27, and power supply pins
	IOL2	—	20	mA	P21, P26, and P27
"L" level average output current	IOLAV1		4	mA	Average value (operating current × operating rate) Except P21, P26, P27, and power supply pins
	IOLAV2		8	mA	Average value (operating current × operating rate) P21, P26, and P27
"L" level total output current	ΣIOL	—	80	mA	
"L" level total average output current	$\Sigma$ Iolav	_	40	mA	Average value (operating current × operating rate)
"H" level output current	Іон1	—	-5	mA	Except P30 and power supply pins
	Іон2		-10	mA	P30

(Continued)

#### (Continued)

(Vss = 0.0 V)

Parameter	Symbol	Va	lue	Unit	Remarks	
Farameter	Symbol	Min.	Max.	Unit	Reinarks	
(11)	Іонаv1	_	-2	mA	Average value (operating current × operating rate) Except P30 and power supply pins	
"H" level average output current	Іонаv2		-4	mA	Average value (operating current × operating rate) P30	
"H" level total output current	∑Іон		-20	mA		
"H" level total average output current	∑Іона∨		-10	mA	Average value (operating current × operating rate)	
Power consumption	PD		300	mW		
Operating temperature	ΤΑ	-40	+85	°C		
Storage temperature	Tstg	-55	+150	°C		

Precautions: Permanent device damage may occur if the above "Absolute Maximum Ratings" are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### 2. Recommended Operating Conditions

(Vss = 0.0 V)

Parameter	Symbol	Value		Unit	Remarks
Falameter	Symbol	Min.	Max.	Unit	itemarks
		2.2* <sup>1</sup>	6.0	V	Guaranteed normal operation range, applicable to the mask ROM products
Power supply voltage	Vcc	2.7*1	6.0	V	MB89P185/PV180
		1.5	6.0	V	RAM data holding assurance range in stop mode
Power supply voltage for LCD	V1 to V3	Vss	Vcc*2	V	V1 to V3 pins
Operating temperature	TA	-40	+85	°C	

\*1: The minimum operating power supply voltage varies with the operating frequency and execution time (instruction cycle).

\*2: The liquid-crystal power supply range and optimum value vary depending on the characteristics of the liquidcrystal display element used.

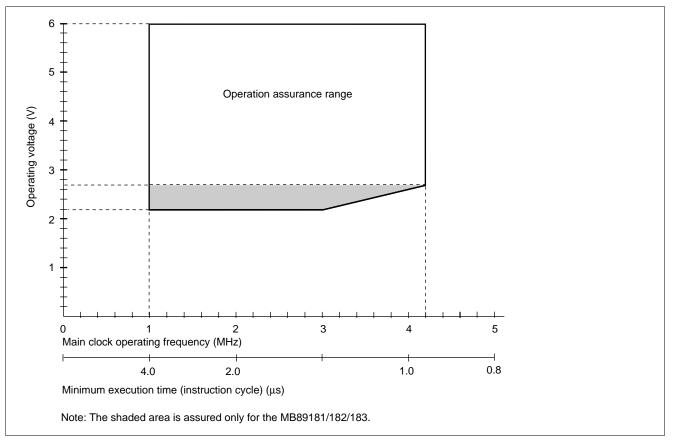


Figure 1 Operating Voltage vs. Main Clock Operating Frequency

### 3. DC Characteristics

				= +5.0 V, <i>F</i>	Value	s = 0.0 V,		0°C to +85°C)
Parameter	Symbol	Pin	Condition	Min.	Тур.	Max.	Unit	Remarks
"H" level input	Vін	P00 to P07, P10 to P17, P20 to P27		0.7 Vcc	_	Vcc + 0.3	V	CMOS input
voltage	Vihs	RST, MODA, EC, SI, SCK, INT10 to INT13, INT20 to INT27		0.8 Vcc	_	Vcc + 0.3	V	Hysteresis input
	VIL	P00 to P07, P10 to P17, P20 to P27		V <sub>ss</sub> – 0.3	_	0.3 Vcc	V	CMOS input
L" level input voltage VILS RST, MODA, EC, SI, SCK, VILS INT10 to INT13, INT20 to INT27		V <sub>ss</sub> – 0.3	_	0.2 Vcc	V	Hysteresis input		
Open-drain output pin application voltage	VD	P20 to P27, P40 to P47, P50 to P57		Vss – 0.3	_	Vss + 6.0	V	Without pull- up resistor
"H" level output	Vон1	P00 to P07, P10 to P17	Iон = −2.0 mA	2.4		_	V	
voltage	Vон2	P30	Іон = –6.0 mA	4.0	_	_	V	
"L" level output voltage	Vol	P00 to P07, P10 to P17, P20, P22 to P25, P30 to P32, P40 to P47, P50 to P57	IoL = +1.8 mA		_	0.4	V	
	Vol2	P21, P26, P27	lo∟ = +8.0 mA			0.4	V	
	Vol3	RST	lo∟ = +4.0 mA			0.4	V	
Input leakage current	ILII	MODA, P00to P07, P10 to P17, P30 to P32	0.0 V < V1 < Vcc	_	_	±5	μΑ	Without pull- up resistor
(Hi-z output leakagecurrent)	ILI2	P20 to P27, P40 to P47, P50 to P57	0.0 V < VI < 6 V	_	_	±1	μA	Without pull- up resistor
Pull-up resistance	Rpull	P00 to P07, P10 to P17, P20 to P27, P40 to P47, P50 to P57, RST	V1 = 0.0 V	25	50	100	kΩ	Without pull- up resistor
Common output impedance	Rvсом	COM0 to COM3	V1 to V3 = 5.0 V		_	2.5	kΩ	
Segment output impedance	Rvseg	SEG0 to SEG31	V1 to V3 = 5.0 V		_	15	kΩ	

 $\Lambda L$ V QE°C) 100C +

(Continued)

(Continued)

<b>-</b>				)	Value	,		
Parameter	Symbol	Pin	Condition	Min.	Тур.	Max.	Unit	Remarks
LCD divided resistor value	RLCD	—	Between Vcc and Vss	300	500	750	kΩ	
LCD controller/ driver leakage current		V1 to V3, COM0 to COM3, SEG0 to SEG31	_	_	_	±1	μA	
	Icc1		$F_{CH} = 4.2 \text{ MHz}$ $V_{CC} = 5.0 \text{ V}$ $t_{inst}^{*2} = 0.95 \ \mu s$	_	3.0	4.5	mA	MB89181/ 182/183/ PV180
			<ul> <li>Main clock operation mode</li> </ul>		3.8	6.0	mA	MB89P185
	Icc2	-	F <sub>CH</sub> = 4.2 MHz V <sub>CC</sub> = 3.0 V $t_{inst}^{*2}$ = 15.2 µs • Main clock	_	0.25	0.4	mA	MB89181/ 182/183/ PV180
			operation mode		0.85	1.4	mA	MB89P185
	Iccl		$F_{CL} = 32.768$ kHz $V_{CC} = 3.0 V$ $t_{inst}^{*2} = 61 \mu s$	_	0.05	0.1	mA	MB89181/ 182/183/ PV180
			<ul> <li>Subclock operation mode</li> </ul>	_	0.65	1.1	mA	MB89P185
Power supply current <sup>*2</sup>	Iccs1	Vcc	$F_{CH} = 4.2 \text{ MHz}$ $V_{CC} = 5.0 \text{ V}$ $t_{inst}^{2} = 0.95 \mu\text{s}$ $\bullet \text{ Main clock}$ $sleep mode$		0.8	1.2	mA	
	Iccs2		$\label{eq:Fch} \begin{array}{l} F_{CH} = 4.2 \; MHz \\ V_{CC} = 3.0 \; V \\ t_{inst}^{ 2} = 15.2 \; \mu s \\ \bullet \; Main \; clock \\ sleep \; mode \end{array}$	_	0.2	0.3	mA	
	IccsL		$\begin{array}{l} F_{CL} = 32.768 \ kHz \\ V_{CC} = 3.0 \ V \\ t_{inst^{*2}} = 61 \ \mu s \\ \bullet \ Subclock \ mode \end{array}$	_	25	50	μA	
	Ісст		F <sub>CL</sub> = 32.768 kHz V <sub>CC</sub> = 3.0 V ● Watch mode	_	10	15	μA	
	loou		T <sub>A</sub> = +25°C Vcc = 5.0 V		0.1	1	μA	MB89181/ 182/183
	Іссн		• Stop mode	_	0.1	10	μΑ	MB89PV18 0/P185
Input capacitance	CIN	Other Vcc and Vss	f = 1 MHz	_	10		pF	

\*1: The measurement conditions of power supply current are as follows: the external clock, open output pins, and the external LCD dividing resistor. In the case of the MB89PV180, the current consumed by the connected EPROM and ICE is not included.

\*2: For information on tinst, see "(4) Instruction Cycle" in "4. AC Characteristics."

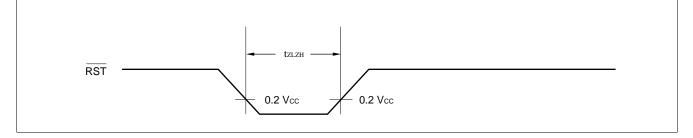
Note: For pins which serve as the segment (SEG8 to SEG31) and ports (P10 to P17, P40 to P47, and P50 to P57), see the port parameter when these pins are used as ports and the segment parameter when they are used as segment pins.

#### 4. AC Characteristics

#### (1) Reset Timing

 $(V_{SS} = 0.0 \text{ V}, \text{ } \text{T}_{A} = -40^{\circ}\text{C to } +85^{\circ}\text{C})$ 

Parameter	Symbol Condition		Valu	ue	Unit	Remarks
Farameter	Symbol	Condition	Min.	Max.	Onic	Remarks
RST "L" pulse width	tzlzн		48 theyl		ns	

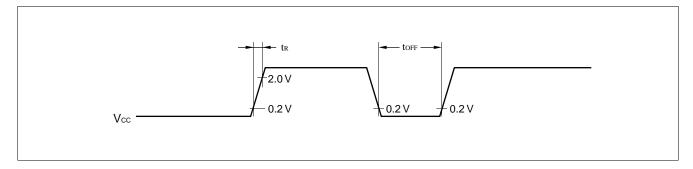


#### (2) Power-on Reset

 $(V_{SS} = 0.0 \text{ V}, \text{ } \text{T}_{A} = -40^{\circ}\text{C to } +85^{\circ}\text{C})$ 

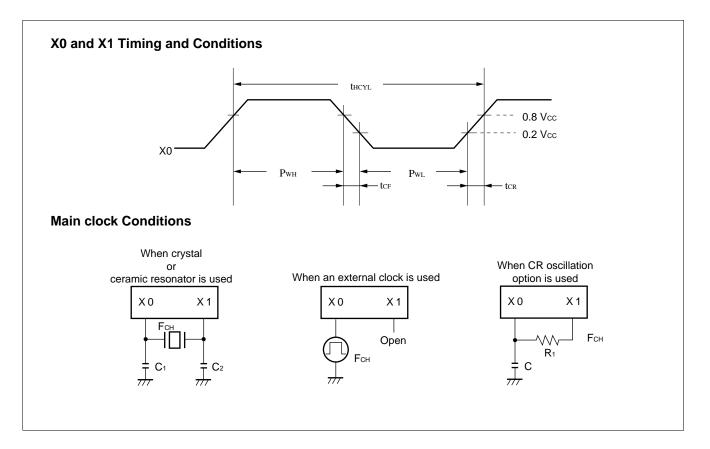
Parameter	Symbol	Condition	Value		Unit	Remarks	
Falameter	Symbol	Condition	Min.	Max.	Unit	Remarks	
Power supply rising time	tR		—	50	ms	Power-on reset function only	
Power supply cut-off time	toff		1		ms	Due to repeated operations	

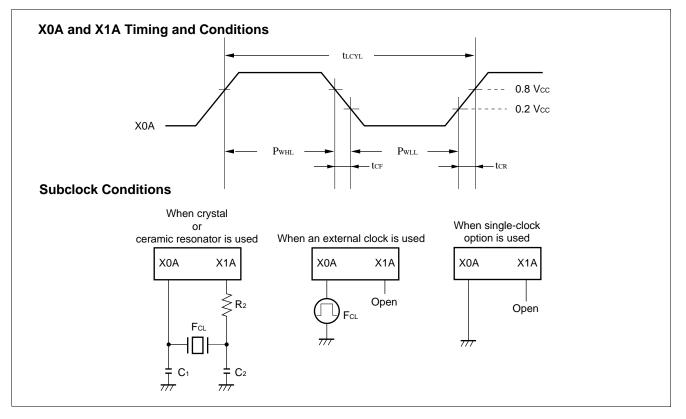
Note: Make sure that power supply rises within the selected oscillation stabilization time. If power supply voltage needs to be varied in the course of operation, a smooth voltage rise is recommended.



#### (3) Clock Timing

 $(V_{SS} = 0.0 \text{ V}, \text{ } \text{T}_{A} = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C})$ Value Symbol Pin Unit Remarks Parameter Min. Тур. Max. X0, X1 1 \_\_\_\_ Fсн 4.2 MHz Main clock **Clock frequency** Fc∟ X0A, X1A \_\_\_\_ 32.768 \_\_\_\_ kHz Subclock X0, X1 Main clock **t**HCYL 238 1000 \_\_\_\_ ns Clock cycle time X0A, X1A Subclock 30.5 **t**LCYL \_\_\_\_ \_\_\_\_ μs Рwн X0 20 ns \_\_\_\_\_ Pwl Input clock pulse width  $\mathbf{P}_{\mathsf{WHL}}$ X0A 15.2 External clock \_\_\_\_\_ μs  $\mathbf{P}_{\mathsf{WLL}}$ Input clock pulse rising/ **t**cr X0, X0A 10 ns falling time **t**CF





#### (4) Instruction Cycle

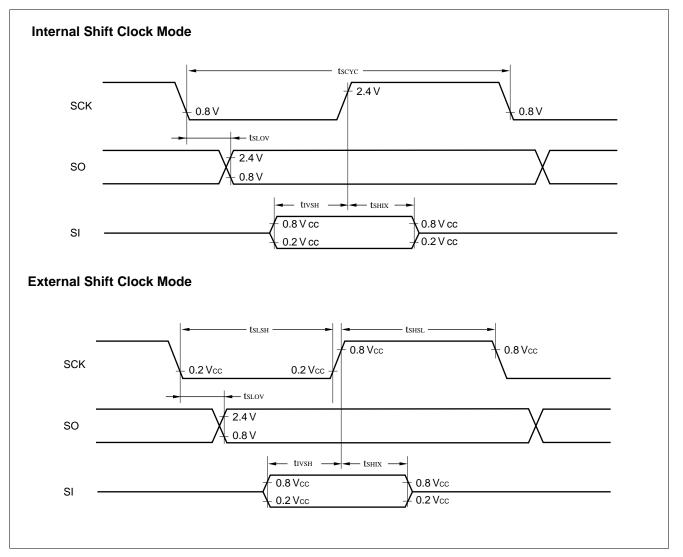
Parameter	Symbol	Value (typical)	Unit	Remarks
Instruction cycle	tinst	4/Fсн, 8/Fсн, 16/Fсн, 64/Fсн	μs	(4/F <sub>CH</sub> ) $t_{inst} = 0.95 \ \mu s$ when operating at F <sub>CH</sub> = 4.2 MHz
(minimum execution time)	unst	2/FcL	μs	$t_{\text{inst}}$ = 61.036 $\mu s$ when operating at FcL = 32.768 kHz

#### (5) Serial I/O Timing

					ie		,
Parameter	Symbol	Pin	Condition	Min.	Max.	Unit	Remarks
Serial clock cycle time	tscyc	SCK		2 tinst*	_	μs	
$SCK \downarrow \to SO \text{ time}$	<b>t</b> slov	SCK, SO	Internal shift	-200	200	ns	
Valid SI $\rightarrow$ SCK $\uparrow$	tıvsн	SI, SCK	clock mode	0.5 tinst*	—	μs	
$SCK \uparrow \to valid \ SI \ hold \ time$	tsнix	SCK, SI	-	0.5 tinst*	_	μs	
Serial clock "H" pulse width	<b>t</b> shsl	SCK		<b>1 t</b> inst*	—	μs	
Serial clock "L" pulse width	<b>t</b> slsh	SCK	-	<b>1 t</b> inst*	—	μs	
$SCK \downarrow \to SO \text{ time}$	<b>t</b> slov	SCK, SO	External shift clock mode	0	200	ns	
Valid SI $\rightarrow$ SCK $\uparrow$	tıvsн	SI, SCK		0.5 <b>t</b> inst*	—	μs	
$SCK \uparrow \to valid \; SI \; hold \; time$	<b>t</b> shix	SCK, SI	-	0.5 <b>t</b> inst*	—	μs	

#### (Vcc = +5.0 V $\pm$ 10%, AVss = Vss= 0.0 V, T<sub>A</sub> = -40°C to +85°C)

\* : For information on tinst, see "(4) Instruction Cycle."

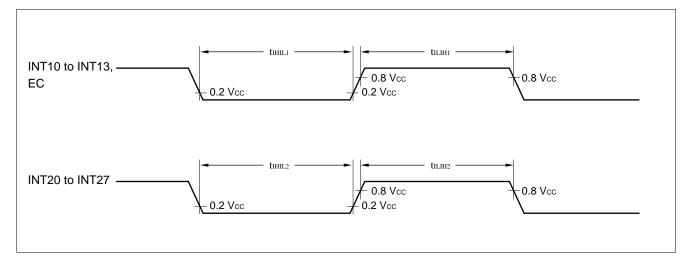


#### (6) Peripheral Input Timing

Parameter	Symbol	Pin	Value		Unit	Remarks
			Min.	Max.	Unit	Remarks
Peripheral input "H" pulse width 1	<b>t</b> ILIH1	INT10 to INT13, EC	1 tinst*		μs	
Peripheral input "L" pulse width 1	tiHIL1	INT10 to INT13, EC	1 tinst*		μs	
Peripheral input "H" pulse width 2	tilih2	INT20 to INT27	2 tinst*		μs	
Peripheral input "L" pulse width 2	tihil2	INT20 to INT27	2 tinst*		μs	

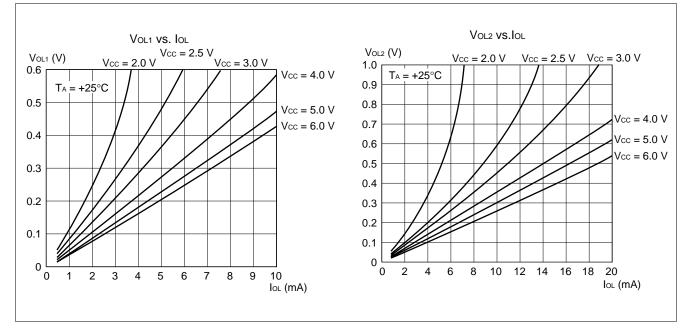
 $(V_{CC} = +5.0 \text{ V} \pm 10\%, \text{ AV}_{SS} = \text{V}_{SS} = 0.0 \text{ V}, \text{ T}_{A} = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C})$ 

\* : For information on tinst, see "(4) Instruction Cycle."

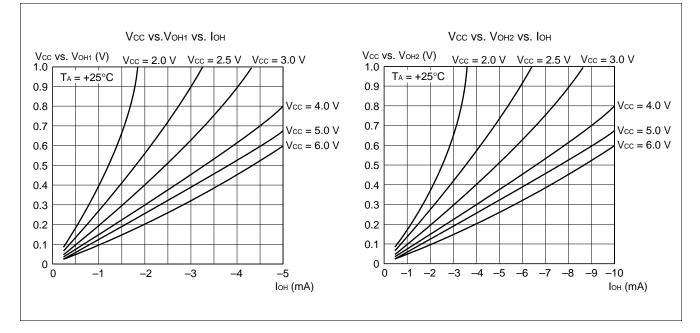


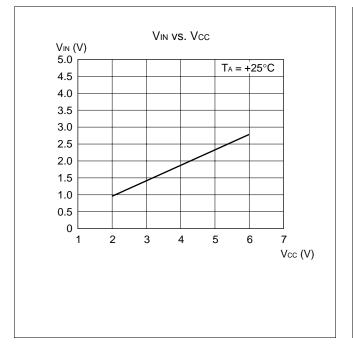
## ■ EXAMPLE CHARACTERISTICS

#### (1) "L" level Output Voltage

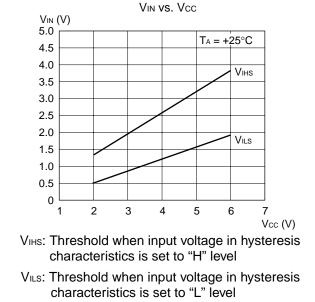


#### (2) "H" level Output Voltage



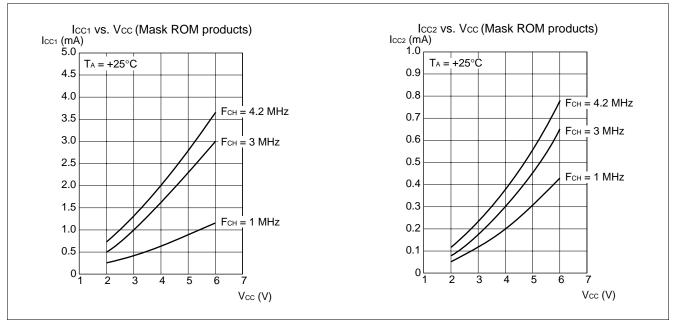


### (3) "H" Level Input Voltage/"L" Level Input Voltage (CMOS Input)



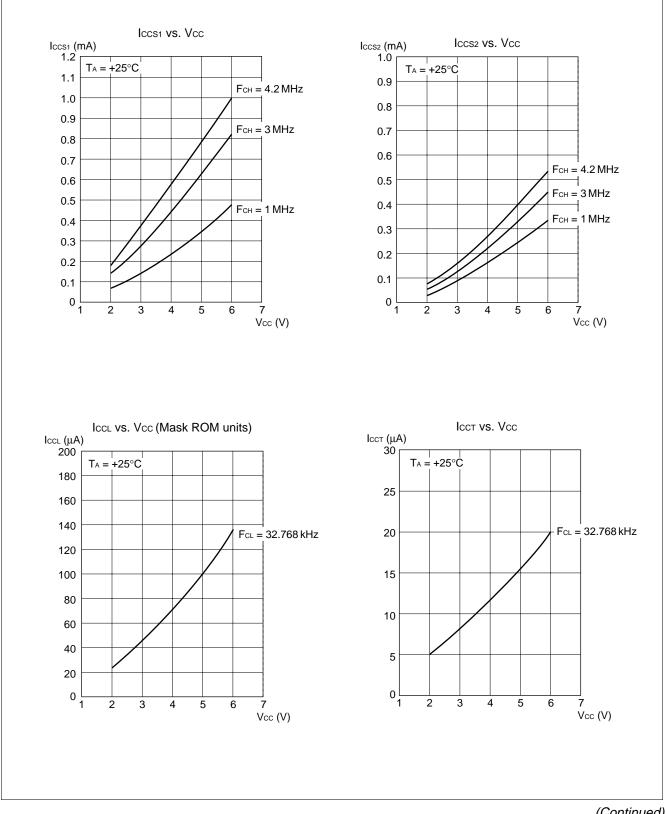
# (4) "H" Level Input Voltage/"L" Level Input Voltage (Hysteresis Input)

# (5) Power Supply Current (External Clock)

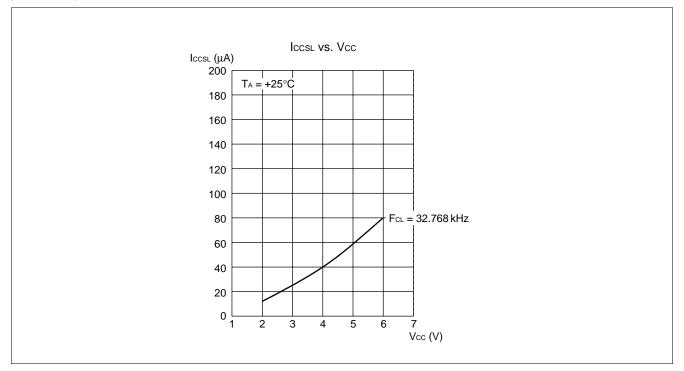




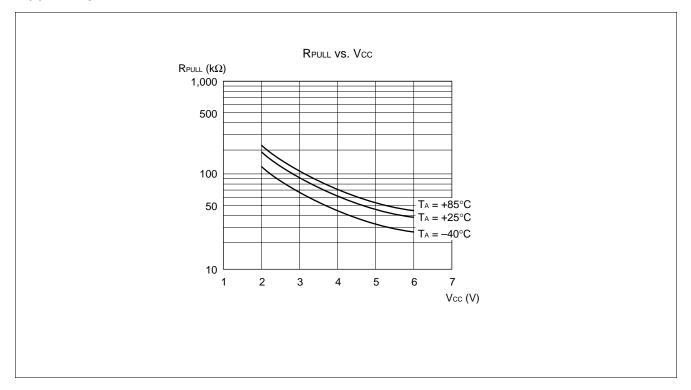
### (Continued)



# (Continued)



### (6) Pull-up Resistance Value



# ■ INSTRUCTIONS

Execution instructions can be divided into the following four groups:

- Transfer
- Arithmetic operation
- Branch
- Others

Table 1 lists symbols used for notation of instructions.

Symbol	Meaning
dir	Direct address (8 bits)
off	Offset (8 bits)
ext	Extended address (16 bits)
#vct	Vector table number (3 bits)
#d8	Immediate data (8 bits)
#d16	Immediate data (16 bits)
dir: b	Bit direct address (8:3 bits)
rel	Branch relative address (8 bits)
@	Register indirect (Example: @A, @IX, @EP)
A	Accumulator A (Whether its length is 8 or 16 bits is determined by the instruction in use.)
AH	Upper 8 bits of accumulator A (8 bits)
AL	Lower 8 bits of accumulator A (8 bits)
Т	Temporary accumulator T (Whether its length is 8 or 16 bits is determined by the instruction in use.)
TH	Upper 8 bits of temporary accumulator T (8 bits)
TL	Lower 8 bits of temporary accumulator T (8 bits)
IX	Index register IX (16 bits)

#### Table 1 Instruction Symbols

(Continued)

Symbol	Meaning
EP	Extra pointer EP (16 bits)
PC	Program counter PC (16 bits)
SP	Stack pointer SP (16 bits)
PS	Program status PS (16 bits)
dr	Accumulator A or index register IX (16 bits)
CCR	Condition code register CCR (8 bits)
RP	Register bank pointer RP (5 bits)
Ri	General-purpose register Ri (8 bits, i = 0 to 7)
×	Indicates that the very $\times$ is the immediate data. (Whether its length is 8 or 16 bits is determined by the instruction in use.)
(×)	Indicates that the contents of $\times$ is the target of accessing. (Whether its length is 8 or 16 bits is determined by the instruction in use.)
(( × ))	The address indicated by the contents of $\times$ is the target of accessing. (Whether its length is 8 or 16 bits is determined by the instruction in use.)

Columns indicate the following:

Mnemonic:	Assembler notation of an instruction
~:	Number of instructions
#:	Number of bytes
Operation:	Operation of an instruction
TL, TH, AH:	A content change when each of the TL, TH, and AH instructions is executed. Symbols in the column indicate the following:
	<ul> <li>"-" indicates no change.</li> <li>dH is the 8 upper bits of operation description data.</li> <li>AL and AH must become the contents of AL and AH immediately before the instruction is executed.</li> <li>00 becomes 00.</li> </ul>
N, Z, V, C:	An instruction of which the corresponding flag will change. If + is written in this column, the relevant instruction will change its corresponding flag.
OP code:	Code of an instruction. If an instruction is more than one code, it is written according to the following rule:
	Example: 48 to 4F $\leftarrow$ This indicates 48, 49, 4F.

Mnemonic	~	#	Operation	TL	TH	AH	NZVC	OP code
MOV dir,A	3	2	$(dir) \leftarrow (A)$	_	_	_		45
MOV @IX +off,A	4	2	$((IX) + off) \leftarrow (A)$	_	-	—		46
MOV ext,A	4	3	$(ext) \leftarrow (A)$	_	_	—		61
MOV @EP,A	3	1	( (EP) ) ← (A)	_	_	_		47
MOV Ri,A	3	1	$(Ri) \leftarrow (A)$	_	_	_		48 to 4F
MOV A,#d8	2	2	$(A) \leftarrow dB'$	AL	_	_	++	04
MOV A,dir	3	2	$(A) \leftarrow (dir)$	AL	_	_	++	05
MOV A, @IX +off	4	2	$(A) \leftarrow ((IX) + off)$	AL	_	_	++	06
MOV A,ext	4	3	$(A) \leftarrow (ext)$	AL	_	_	++	60
MOV A,@A	3	1	$(A) \leftarrow ((A))$	AL	_	_	++	92
MOV A,@EP	3	1	$(A) \leftarrow ((EP))$	AL	_	_	++	07
MOV A,Ri	3	1	$(A) \leftarrow (Ri)$	AL	_	_	++	08 to 0F
MOV dir,#d8	4	3	$(dir) \leftarrow d8$	_	_	_		85
MOV @IX +off,#d8	5	3	$((IX) + off) \leftarrow d8$	_	_	_		86
MOV @EP,#d8	4	2	$((EP)) \leftarrow d8$	_				87
MOV @LI,#d8	4	2	$(Ri) \leftarrow d8$	_	_	_		88 to 8F
MOV NI,#00 MOVW dir,A	4	2		_	_	_		D5
	4 5	2	$(dir) \leftarrow (AH), (dir + 1) \leftarrow (AL)$	-	_	_		D5 D6
MOVW @IX +off,A	5	2	$((IX) + off) \leftarrow (AH),$	-	_	_		00
	_	~	$((IX) + off + 1) \leftarrow (AL)$					<b>D</b> 4
MOVW ext,A	5	3	$(ext) \leftarrow (AH), (ext + 1) \leftarrow (AL)$	-	_	_		D4
MOVW @EP,A	4	1	$((EP)) \leftarrow (AH), ((EP) + 1) \leftarrow (AL)$	_	-	—		D7
MOVW EP,A	2	1	$(EP) \leftarrow (A)$	_	_	—		E3
MOVW A,#d16	3	3	$(A) \leftarrow d16$	AL	AH	dH	++	E4
MOVW A,dir	4	2	$(AH) \leftarrow (dir), (AL) \leftarrow (dir + 1)$	AL	AH	dH	++	C5
MOVW A,@IX +off	5	2	$(AH) \leftarrow ((IX) + off),$	AL	AH	dH	++	C6
	_	-	$(AL) \leftarrow ((IX) + off + 1)$					
MOVW A,ext	5	3	$(AH) \leftarrow (ext), (AL) \leftarrow (ext + 1)$	AL	AH	dH	++	C4
MOVW A,@A	4	1	$(AH) \leftarrow (\ (A)\ ),\ (AL) \leftarrow (\ (A)\ )+1)$	AL	AH	dH	++	93
MOVW A,@EP	4	1	$(AH) \leftarrow ((EP)), (AL) \leftarrow ((EP) + 1)$	AL	AH	dH	++	C7
MOVW A,EP	2	1	$(A) \leftarrow (EP)$	—	—	dH		F3
MOVW EP,#d16	3	3	(EP) ← d16	—	—	—		E7
MOVW IX,A	2	1	$(IX) \leftarrow (A)$	_	-	—		E2
MOVW A,IX	2	1	$(A) \leftarrow (IX)$	_	-	dH		F2
MOVW SP,A	2	1	$(SP) \leftarrow (A)$	_	-	—		E1
MOVW A,SP	2	1	$(A) \leftarrow (SP)$	_	-	dH		F1
MOV @A,T	3	1	$((A)) \leftarrow (T)$	_	—	—		82
MOVW @A,T	4	1	$((A)) \leftarrow (TH), ((A) + 1) \leftarrow (TL)$	_	—	—		83
MOVW IX,#d16	3	3	$(IX) \leftarrow d16$	_	_	_		E6
MOVW A,PS	2	1	$(A) \leftarrow (PS)$	_	_	dH		70
MOVW PS,A	2	1	$(PS) \leftarrow (A)$	_	_	_	++++	71
MOVW SP,#d16	3	3	$(SP) \leftarrow d16$	_	_	_		E5
SWAP	2	1	ÌAH́) ↔ (AL)	_	_	AL		10
SETB dir: b	4	2	(dir):́ b ← 1 ′	_	_	_		A8 to AF
CLRB dir: b	4	2	$(dir)$ : b $\leftarrow$ 0	_	_	_		A0 to A7
XCH A,T	2	1	$(AL) \leftrightarrow (TL)$	AL	_	_		42
XCHW A,T	3	1	$(A) \leftrightarrow (T)$	AL	AH	dH		43
XCHW A,EP	3	1	$(A) \leftrightarrow (EP)$	_	_	dH		F7
XCHW A,IX	3	1	$(A) \leftrightarrow (IX)$	_	_	dH		F6
XCHW A,SP	3	1	$(A) \leftrightarrow (SP)$	_	_	dH		F5
MOVW A,PC	2	1	$(A) \leftarrow (PC)$	_	_	dH		F0
	<u> </u>					GIT		10

 Table 2
 Transfer Instructions (48 instructions)

Notes: • During byte transfer to A, T ← A is restricted to low bytes.
• Operands in more than one operand instruction must be stored in the order in which their mnemonics are written. (Reverse arrangement of F<sup>2</sup>MC-8 family)

Mnemonic	~	#	Operation	TL	тн	AH	NZVC	OP code
ADDC A,Ri	3	1	$(A) \leftarrow (A) + (Ri) + C$	_	Ι	_	+ + + +	28 to 2F
ADDC A,#d8	2	2	$(A) \leftarrow (A) + d8 + C$	-	-	—	++++	24
ADDC A,dir	3	2	$(A) \leftarrow (A) + (dir) + C$	-	-	—	++++	25
ADDC A,@IX +off	4	2	$(A) \leftarrow (A) + ((IX) + off) + C$	_	_	—	+ + + +	26
ADDC A,@EP	3	1	$(A) \leftarrow (A) + (\ (EP)\ ) + C$	-	-	—	++++	27
ADDCW A	3	1	$(A) \leftarrow (A) + (T) + C$	-	-	dH	++++	23
ADDC A	2	1	$(AL) \leftarrow (AL) + (TL) + C$	-	-	—	++++	22
SUBC A,Ri	3	1	$(A) \leftarrow (A) - (Ri) - C$	_	_	—	+ + + +	38 to 3F
SUBC A,#d8	2	2	$(A) \leftarrow (A) - d8 - C$	-	-	—	++++	34
SUBC A,dir	3	2	$(A) \leftarrow (A) - (dir) - C$	-	-	—	++++	35
SUBC A,@IX +off	4	2	$(A) \leftarrow (A) - ((IX) + off) - C$	-	-	—	+ + + +	36
SUBC A,@EP	3	1	$(A) \leftarrow (A) - (\ (EP)\ ) - C$	_	_	—	+ + + +	37
SUBCW A	3	1	$(A) \leftarrow (T) - (A) - C$	_	_	dH	+ + + +	33
SUBC A	2	1	$(AL) \leftarrow (TL) - (AL) - C$	_	_	—	+ + + +	32
INC Ri	4	1	(Ri) ← (Ri) + 1	_	_	—	+++-	C8 to CF
INCW EP	3	1	$(EP) \leftarrow (EP) + 1$	_	_	—		C3
INCW IX	3	1	$(IX) \leftarrow (IX) + 1$	_	—	—		C2
INCW A	3	1	$(A) \leftarrow (A) + 1$	_	_	dH	+ +	C0
DEC Ri	4	1	$(Ri) \leftarrow (Ri) - 1$	_	_	—	+++-	D8 to DF
DECW EP	3	1	$(EP) \leftarrow (EP) - 1$	_	_	—		D3
DECW IX	3	1	$(IX) \leftarrow (IX) - 1$	_	_	_		D2
DECW A	3	1	$(A) \leftarrow (A) - 1$	_	_	dH	++	D0
MULU A	19	1	$(A) \leftarrow (AL) \times (TL)$	_	_	dH		01
DIVU A	21	1	$(A) \leftarrow (T) / (AL), MOD \rightarrow (T)$	dL	00	00		11
ANDW A	3	1	$(A) \leftarrow (A) \land (T)$	_	_	dH	+ + R –	63
ORW A	3	1	$(A) \leftarrow (A) \lor (T)$	_	_	dH	+ + R –	73
XORW A	3	1	$(A) \leftarrow (A) \forall (T)$	_	_	dH	+ + R –	53
CMP A	2	1	(TL) – (ÁL)	_	_	_	++++	12
CMPW A	3	1	(T) - (A)	_	_	_	++++	13
RORC A	2	1	$\rightarrow$ C $\rightarrow$ A $\neg$	-	_	-	+ + - +	03
ROLC A	2	1		_	_	_	++-+	02
CMP A,#d8	2	2	(A) - d8	_	-	-	++++	14
CMP A,dir	3	2	(A) - (dir)	_	—	-	++++	15
CMP A,@EP	3	1	(A) – ( (EP) )	-	—	-	++++	17
CMP A,@IX +off	4	2	(A) - ((IX) + off)	-	-	—	+ + + +	16
CMP A,Ri	3	1	(A) – (Ri)	-	-	—	+ + + +	18 to 1F
DAA	2	1	Decimal adjust for addition	_	_	—	++++	84
DAS	2	1	Decimal adjust for subtraction	_	_	—	++++	94
XOR A	2	1	$(A) \leftarrow (AL) \forall (TL)$	-	-	—	+ + R –	52
XOR A,#d8	2	2	$(A) \leftarrow (AL) \forall d8$	_	_	—	+ + R –	54
XOR A,dir	3	2	$(A) \leftarrow (AL) \forall (dir)$	_	—	-	+ + R –	55
XOR A,@EP	3	1	$(A) \leftarrow (AL) \; \forall \; (\; (EP) \;)$	_	—	-	+ + R –	57
XOR A,@IX +off	4	2	$(A) \leftarrow (AL) \forall ((IX) + off)$	_	—	-	+ + R –	56
XOR A,Ri	3	1	$(A) \leftarrow (AL) \ \forall \ (Ri)$	_	—	—	+ + R –	58 to 5F
AND A	2	1	$(A) \leftarrow (AL) \land (TL)$	_	—	—	+ + R –	62
AND A,#d8	2	2	$(A) \leftarrow (AL) \land d8$	_	—	—	+ + R –	64
AND A,dir	3	2	$(A) \leftarrow (AL) \land (dir)$	-	_	-	+ + R –	65
	1	i	1			1	I.	(Continued)

Table 3 Arithmetic Operation Instructions (62 instructions)

Mnemonic	2	#	Operation	TL	TH	AH	NZVC	OP code
AND A,@EP	3	1	$(A) \leftarrow (AL) \land ((EP))$	_	_	_	+ + R –	67
AND A,@IX +off	4	2	$(A) \leftarrow (AL) \land ((IX) + off)$	_	_	—	+ + R –	66
AND A,Ri	3	1	$(A) \leftarrow (AL) \land (Ri)$	—	_	—	+ + R –	68 to 6F
OR A	2	1	$(A) \leftarrow (AL) \lor (TL)$	_	_	_	+ + R –	72
OR A,#d8	2	2	$(A) \leftarrow (AL) \lor d8$	_	_	_	+ + R –	74
OR A,dir	3	2	$(A) \leftarrow (AL) \lor (dir)$	_	_	—	+ + R –	75
OR A,@EP	3	1	$(A) \leftarrow (AL) \lor ((EP))$	_	_	_	+ + R –	77
OR A,@IX +off	4	2	$(A) \leftarrow (AL) \lor ((IX) + off)$	_	_	_	+ + R –	76
OR A,Ri	3	1	$(A) \leftarrow (AL) \lor (Ri)$	_	_	_	+ + R –	78 to 7F
CMP dir,#d8	5	3	(dir) – d8	_	_	_	++++	95
CMP @EP,#d8	4	2	( (ÉP) ) – d8	_	_	_	++++	97
CMP @IX +off,#d8	5	3	((IX) + off) - d8	_	_	_	++++	96
CMP Ri,#d8	4	2	(Ri) – d8	_	_	_	++++	98 to 9F
INCW SP	3	1	(SP) ← (ŚP) + 1	—	—	—		C1
DECW SP	3	1	$(SP) \leftarrow (SP) - 1$	-	-	-		D1

Table 4	Branch Instructions	(17 instructions)
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Mnemonic	~	#	Operation	TL	ΤН	AH	NZVC	OP code
BZ/BEQ rel	3	2	If Z = 1 then PC $\leftarrow$ PC + rel	_	-	-		FD
BNZ/BNE rel	3	2	If Z = 0 then PC $\leftarrow$ PC + rel	_	_	_		FC
BC/BLO rel	3	2	If C = 1 then PC $\leftarrow$ PC + rel	_	_	_		F9
BNC/BHS rel	3	2	If C = 0 then PC $\leftarrow$ PC + rel	_	_	_		F8
BN rel	3	2	If N = 1 then PC $\leftarrow$ PC + rel	_	_	_		FB
BP rel	3	2	If N = 0 then PC $\leftarrow$ PC + rel	_	_	_		FA
BLT rel	3	2	If V $\forall$ N = 1 then PC $\leftarrow$ PC + rel	_	_	_		FF
BGE rel	3	2	If V $\forall$ N = 0 then PC $\leftarrow$ PC + rel	_	_	_		FE
BBC dir: b,rel	5	3	If (dir: b) = 0 then PC $\leftarrow$ PC + rel	_	_	_	-+	B0 to B7
BBS dir: b,rel	5	3	If (dir: b) = 1 then PC $\leftarrow$ PC + rel	_	_	_	-+	B8 to BF
JMP @A	2	1	$(\dot{PC}) \leftarrow (A)$	_	_	_		E0
JMP ext	3	3	$(PC) \leftarrow ext$	_	_	_		21
CALLV #vct	6	1	Vector call	_	_	_		E8 to EF
CALL ext	6	3	Subroutine call	_	_	_		31
XCHW A,PC	3	1	$(PC) \leftarrow (A), (A) \leftarrow (PC) + 1$	_	_	dH		F4
RET	4	1	Return from subrountine	—	—	—		20
RETI	6	1	Return form interrupt	-	-	-	Restore	30

Table 5	Other	Instructions	(9	instructions	)
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Mnemonic	~	#	Operation	TL	TH	AH	NZVC	OP code
PUSHW A	4	1		_	_	_		40
POPW A	4	1		_	_	dH		50
PUSHW IX	4	1		_	_	_		41
POPW IX	4	1		—	—	—		51
NOP	1	1		—	—	—		00
CLRC	1	1		—	—	—	R	81
SETC	1	1		—	—	—	S	91
CLRI	1	1		—	—	—		80
SETI	1	1		-	-	-		90

L H	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
0	NOP	SWAP	RET	RETI	PUSHW A	POPW A	MOV A,ext	MOVW A,PS	CLRI	SETI	CLRB dir: 0	BBC dir: 0,rel	INCW A	DECW A	JMP @ A	MOVW A,PC
1	MULU A	DIVU A	JMP addr16	CALL addr16	PUSHW IX	POPW IX	MOV ext,A	MOVW PS,A	CLRC	SETC	CLRB dir: 1	BBC dir: 1,rel	INCW SP	DECW SP	MOVW SP,A	MOVW A,SP
2	ROLC	CMP	ADDC	SUBC	XCH	XOR	AND	OR	MOV	MOV	CLRB	BBC	INCW	DECW	MOVW	MOVW
	A	A	A	A	A, T	A	A	A	@A,T	A,@A	dir: 2	dir: 2,rel	IX	IX	IX,A	A,IX
3	RORC	CMPW	ADDCW	SUBCW	XCHW	XORW	ANDW	ORW	MOVW	MOVW	CLRB	BBC	INCW	DECW	MOVW	MOVW
	A	A	A	A	A, T	A	A	A	@A,T	A,@A	dir: 3	dir: 3,rel	EP	EP	EP,A	A,EP
4	MOV A,#d8	CMP A,#d8	ADDC A,#d8	SUBC A,#d8		XOR A,#d8	AND A,#d8	OR A,#d8	DAA	DAS	CLRB dir: 4	BBC dir: 4,rel	MOVW A,ext	MOVW ext,A	MOVW A,#d16	XCHW A,PC
5	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	CLRB	BBC	MOVW	MOVW	MOVW	XCHW
	A,dir	A,dir	A,dir	A,dir	dir,A	A,dir	A,dir	A,dir	dir,#d8	dir,#d8	dir: 5	dir: 5,rel	A,dir	dir,A	SP,#d16	A,SP
6	MOV	CMP	ADDC	SUBC	MOV @IX	XOR	AND	OR	MOV	CMP	CLRB	BBC	MOVW	MOVW	MOVW	XCHW
	A,@IX +d	A,@IX +d	A,@IX +d	A,@IX +d	+d,A	A,@IX +d	A,@IX +d	A,@IX +d	@IX +d,#d8	@IX +d,#d8	dir: 6	dir: 6,rel	A,@IX +d	@IX +d,A	IX,#d16	A,IX
7	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	CLRB	BBC	MOVW	MOVW	MOVW	XCHW
	A,@EP	A,@EP	A,@EP	A,@EP	@EP,A	A,@EP	A,@EP	A,@EP	@EP,#d8	@EP,#d8	dir: 7	dir: 7,rel	A,@EP	@EP,A	EP,#d16	A,EP
8	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BNC
	A,R0	A,R0	A,R0	A,R0	R0,A	A,R0	A,R0	A,R0	R0,#d8	R0,#d8	dir: 0	dir: 0,rel	R0	R0	#0	rel
9	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BC
	A,R1	A,R1	A,R1	A,R1	R1,A	A,R1	A,R1	A,R1	R1,#d8	R1,#d8	dir: 1	dir: 1,rel	R1	R1	#1	rel
Α	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BP
	A,R2	A,R2	A,R2	A,R2	R2,A	A,R2	A,R2	A,R2	R2,#d8	R2,#d8	dir: 2	dir: 2,rel	R2	R2	#2	rel
В	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BN
	A,R3	A,R3	A,R3	A,R3	R3,A	A,R3	A,R3	A,R3	R3,#d8	R3,#d8	dir: 3	dir: 3,rel	R3	R3	#3	rel
С	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BNZ
	A,R4	A,R4	A,R4	A,R4	R4,A	A,R4	A,R4	A,R4	R4,#d8	R4,#d8	dir: 4	dir: 4,rel	R4	R4	#4	rel
D	MOV A	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BZ
	A,R5	A,R5	A,R5	A,R5	R5,A	A,R5	A,R5	A,R5	R5,#d8	R5,#d8	dir: 5	dir: 5,rel	R5	R5	#5	rel
E	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BGE
	A,R6	A,R6	A,R6	A,R6	R6,A	A,R6	A,R6	A,R6	R6,#d8	R6,#d8	dir: 6	dir: 6,rel	R6	R6	#6	rel
F	MOV	CMP	ADDC	SUBC	MOV	XOR	AND	OR	MOV	CMP	SETB	BBS	INC	DEC	CALLV	BLT
	A,R7	A,R7	A,R7	A,R7	R7,A	A,R7	A,R7	A,R7	R7,#d8	R7,#d8	dir: 7	dir: 7,rel	R7	R7	#7	rel

■ INSTRUCTION MAP

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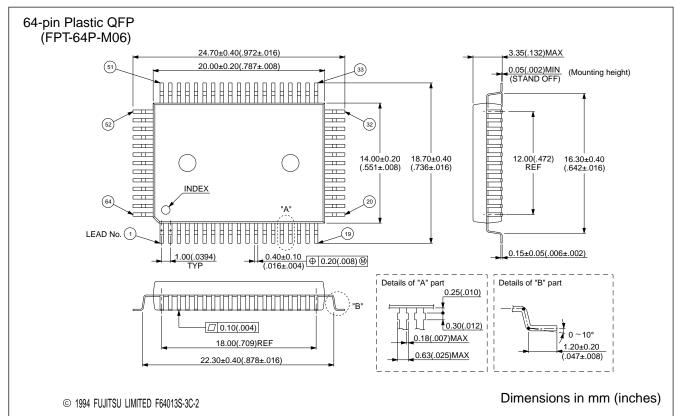
# ■ MASK OPTIONS

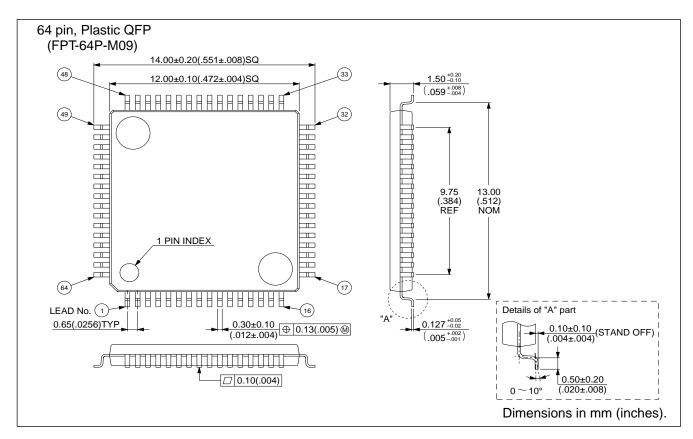
	Part number	MB89181/182/183	MB89P185	MB89PV180
No.	Specifying procedure	Specify when ordering masking	Set with EPROM programmer	Setting not possible
1	Pull-up resistors P00 to P07, P10 to P17	Can be set per pin (P10 to P17 are available only when segment output is not selected.)		
2	Pull-up resistors P40 to P47, P50 to P57	Can be set per pin (Available only when segment output is not selected.)	Fixed to without pull- up resistor	Fixed to without pull- up resistor
3	Pull-up resistors P20 to P27	Can be set per pin	Fixed to without pull- up resistor	
4	Power-on reset With power-on reset Without power-on reset	Selectable	Selectable	Fixed to with power- on reset
5	Selection of oscillation stabilization delay time The initial value of the main clock oscillation stabilization time is selectable by bit value of WTM1 and WTM0.	Selectable           WTM1 WTM0           0         0: 2²/Fсн           0         1: 2¹²/Fсн           1         0: 2¹ <sup>6</sup> /Fсн           1         1: 2¹ <sup>8</sup> /Fсн	Selectable WTM1 WTM0 0 0: 2 <sup>2</sup> /Fсн 0 1: 2 <sup>12</sup> /Fсн 1 0: 2 <sup>16</sup> /Fсн 1 1: 2 <sup>18</sup> /Fсн	Fixed to oscillation stabilization time of 2 <sup>16</sup> /F <sub>CH</sub>
6	Main clock oscillation type Crystal or ceramic oscillator CR	Selectable	Crystal or ceramic oscillator	Crystal or ceramic oscillator
7	Reset pin output With reset output Without reset output	Selectable	Selectable	With reset output
8	Clock mode selection Dual-clock mode Single-clock mode	Selectable	Selectable	Fixed to dual-clock mode
9	Segment output selection 32 segments:No port selection 28 segments:Selection of P17 to P14 24 segments: Selection of P17 to P10 20 segments:Selection of P17 to P10,and P57 to P54 16 segments:Selection of P17 to P10,and P57 to P50 12 segments:Selection of P17 to P10,P57 to P50, and P47 to P44 8 segments: Selection of P17 to P10,P57 to P50, and P47 to P40	Selectable Selects the number of segments.	-102: 28 - -103: 24 - -104: 20 - -105: 16 - -106: 12 -	segments segments segments segments segments segments segments

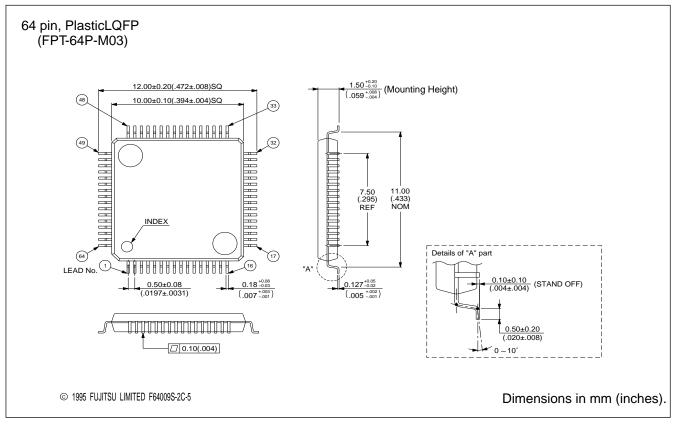
# ■ ORDERING INFORMATION

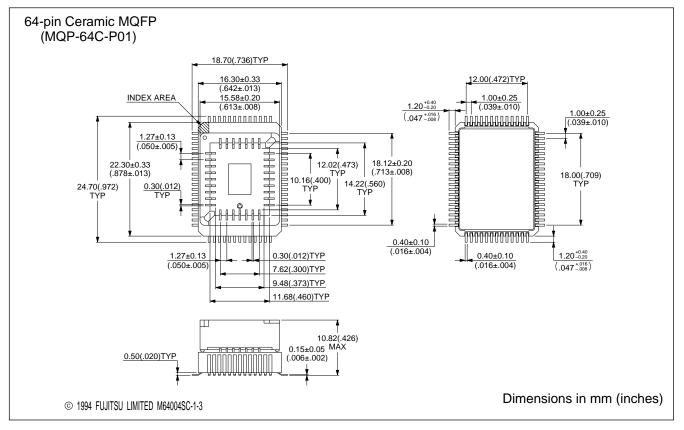
Part number	Package	Remarks
MB89181PF MB89182PF MB89183PF MB89P185PF-101 MB89P185PF-102 MB89P185PF-103 MB89P185PF-104 MB89P185PF-105 MB89P185PF-106 MB89P185PF-107	64-pin Plastic QFP (FPT-64P-M06)	
MB89181FM MB89182FM MB89183FM MB89P185PFM-101 MB89P185PFM-102 MB89P185PFM-103 MB89P185PFM-104 MB89P185PFM-105 MB89P185PFM-106 MB89P185PFM-107	64-pin Plastic QFP (FPT-64P-M09)	
MB89181PFV MB89182PFV MB89183PFV	64-pin Plastic SQFP (FPT-64P-M03)	
MB89PV180CF-101 MB89PV180CF-102 MB89PV180CF-103 MB89PV180CF-104 MB89PV180CF-105 MB89PV180CF-106 MB89PV180CF-107	64-pin Ceramic MQFP (MQP-64C-P01)	

# ■ PACKAGE DIMENSIONS









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